

# xCAT 2.X Monitoring How-to

## 05/08/2009

### Table of Contents

<a href="#">1.0 Introduction</a>	1
<a href="#">2.0 Using xCAT Monitoring Plug-in Infrastructure</a>	1
<a href="#">2.1 xCAT Monitoring Commands and How-to</a>	2
<a href="#">2.1.1 Configure and start monitoring during the node deployment phase</a>	2
<a href="#">2.1.2 Configure and start monitoring after the node is up and running</a>	3
<a href="#">2.2 Define monitoring servers</a>	4
<a href="#">2.3 Enable SNMP monitoring</a>	5
<a href="#">2.4 Enable RMC monitoring</a>	8
<a href="#">2.5 Enable node liveness monitoring</a>	11
<a href="#">2.6 Enable Ganglia monitoring</a>	11
<a href="#">2.7 Enable PCP (Performance Co-Pilot) monitoring</a>	12
<a href="#">2.8 Enable node liveness monitoring with PCP</a>	14
<a href="#">2.9 Create your own monitoring plug-in module</a>	14
<a href="#">3.0 Using xCAT Notification Infrastructure</a>	16

## 1.0 Introduction

There are two monitoring infrastructures introduced in xCAT 2.0. The *xCAT Monitoring Plug-in Infrastructure* allows you to plug-in one or more third party monitoring software such as Ganglia, RMC, SNMP etc. to monitor the xCAT cluster. The *xCAT Notification Infrastructure* allows you to watch for the changes in xCAT database tables.

## 2.0 Using xCAT Monitoring Plug-in Infrastructure

With xCAT 2.0, you can integrate 3rd party monitoring software into your xCAT cluster. The idea is to use monitoring plug-in modules that act as bridges to connect xCAT and the 3rd party software. Though you can write your own monitoring plug-in modules (see section 2.3), over the time, xCAT will supply a list of built-in plug-in modules for the most common monitoring software. They are:

- xCAT (xcatmon.pm) (monitoring node statue using fping. released)
- SNMP (snmpmon.pm) (snmp monitoring. released)
- RMC (rmcmon.pm) (released)
- Ganglia (gangliamon.pm) (released)
- Nagios (nagiosmon.pm)

- Performance Co-pilot (pcpmon.pm)

You can pick one or more monitoring plug-ins to monitor the xCAT cluster. The following sections will demonstrate how to use snmpmon and xcatmon plug-ins.

## 2.1 xCAT Monitoring Commands and How-to

In xCAT, there are 7 commands available for monitoring purpose. They are

Command	Description
monls	list the current or all the monitoring plug-in names, their status and description.
monadd	add a monitoring plug-in to the 'monitoring' table. This will also adds the configuration scripts for the monitoring plug-in, if any, to the 'postscripts' table.
monrm	remove a monitoring plug-in from the 'monitoring' table. It also removes the configuration scripts for the monitoring plug-in from the 'postscripts' table.
moncfg	configure the 3 <sup>rd</sup> party monitoring software on the management server and the service node for the given nodes to include the nodes into the monitoring domain. It does all the necessary configuration changes to prepare the software for monitoring the nodes. The -r option will configure the nodes as well.
mondecfg	deconfigure the 3 <sup>rd</sup> party monitoring software on the management server and the service node for the given nodes to remove the nodes from the monitoring domain. The -r option will deconfigure the nodes as well.
monstart	start 3 <sup>rd</sup> party software on the management server and the service node for the given nodes to monitor the xCAT cluster. It includes starting the daemons. The -r option will start the daemons on the nodes as well.
monstop	stop 3 <sup>rd</sup> party software on the management server and the service node for the given nodes from monitoring the xCAT cluster. The -r will stop the daemons on the nodes as well.

There are 2 ways you can configure the 3<sup>rd</sup> party software to monitor the xCAT cluster. The first way is to configure it on the nodes during the node deployment phase. The second is to configure it after the node is up and running.

### 2.1.1 Configure and start monitoring during the node deployment phase

1. Define the nodes in the xCAT cluster. Please refer to [xCAT 2 cookbook](#) for details.
2. Install the 3<sup>rd</sup> party monitoring software on the management node.

3. Add the 3<sup>rd</sup> party monitoring plug-in software into the images for the service node and the compute node. This involves in copying the software onto `/install/post/otherpkgs/<osver>/<arch>` directory and adding the package names in the 'other package' list for the image profile for the nodes. The image profile is located under `/install/custom/<install|netboot>/<os>` and it defaults to `/opt/xcat/share/xcat/<install|netboot>/<os>`. Please refer to [xCAT 2 How to Install Additional Software](#) for details.

4. Add the monitoring plug-in, say xxx, to the 'monitoring' table.

```
monadd xxx [-n] [-s]
```

where `-n` means that the 3<sup>rd</sup> party software will also be used as the tool to feed the node status. `-s` is for the plug-in specific settings. The node configuration scripts for this monitoring plug-in are added to the 'postscripts' table by this command. Use

```
monls xxx -d
```

command to check for the configuration script names for the monitoring plug-in.

5. Configure monitoring software on the management server for the given nodes.

```
moncfg xxx <nodes>
```

where `nodes` are the all node to be monitored.

6. Deploy the nodes.

```
nodeset; netboot; genimage; packimage; rpower etc.
```

Check the [xCAT 2 cookbook](#) for details on how to deploy diskless or diskfull nodes. The deployment process will run the configuration scripts for the monitoring plug-in which will configure/prepare the nodes for monitoring.

7. Start the monitoring after the node are up

```
monstart xxx
```

Note: If the cluster has hierarchy, then do step 5 and 6 for the monitoring servers first and then repeat them for the compute nodes. Please refer to section 2.2 for defining monitoring servers.

Now the cluster is set up for monitoring using the 3<sup>rd</sup> party software xxx. You can stop the monitoring at any time by using the `monstop` command.

```
monstop xxx or
```

```
monstop xxx -r (-r will stop all the daemons on the nodes as well)
```

### 2.1.2 Configure and start monitoring after the node is up and running

You may want to add monitoring capability after the node is up and running.

For nodes that have local disks, follow the step 2 through step 7 described in above section. The only exception is step 6, instead of deploying the nodes, you need run the following command:

```
updatenode <noderange> (run all the postscripts) or
```

```
updatenode <noderange> otherpkgs, cfg1, cfg2... (run specific postscripts)
```

where `otherpkgs` is used to install the new software and `cfg1, cfg2` etc. are the configuration scripts for the monitoring plug-in. To list the configuration script names do.

```
monls xxx -d
```

Note: run

```
updatenode <noderange> cfg1, cfg2..
```

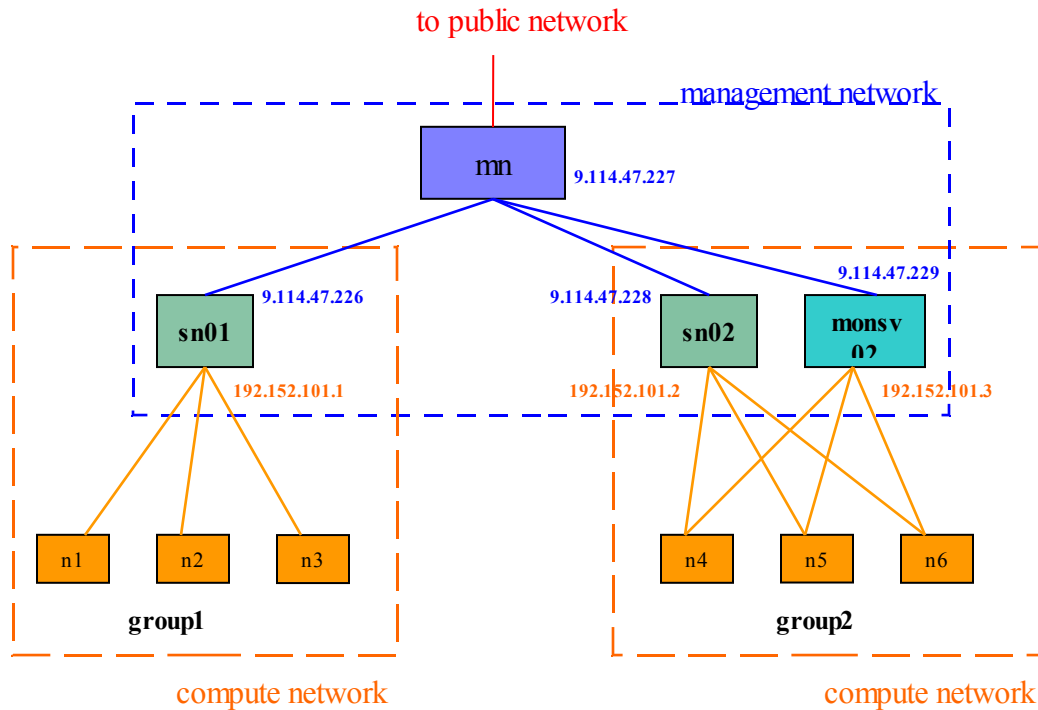
if the 3<sup>rd</sup> parth monitoring software has already been installed.

For diskless nodes, you need to regenerate the image and deploy the nodes again. Just follow step 2 through 7 as described in section 2.1.1.

## **2.2 Define monitoring servers**

You can skip this section if you have a small number of nodes to monitor, or if you prefer the management node (mn) handles the monitoring loads. For a large cluster, it is recommended that you dedicate some nodes as monitoring aggregation points. These nodes are called monitoring servers. You can use the service nodes (sn) as the monitoring servers. The monitoring servers are defined by the 'monserver' column of the **noderes** table. The data in 'monserver' column is a comma separated pairs of host names or ip addresses. The first host name or ip address represents the network adapter on that connects to the mn. The second host name or ip address represents the network adapter that connects to the nodes. If the no data is provided in the 'monserver' column, the values in the 'servicenode' and the 'xcatmaster' columns in the same table will be used. If none is defined, the mn will be used as the monitoring server.

In following example the nodes in `group2` have dedicated monitoring server (monsv02) while the nodes in `group1` use their service node as the monitoring server (sn01).



**Figure 1. Monitoring servers for the nodes**  
 The **noderes** table looks like this for the above cluster.

node	monservers	servicenode	xcatmaster
sv01		9.114.47.227	9.114.47.227
sv02		9.114.47.227	9.114.47.227
monsv02		9.114.47.227	9.114.47.227
group1		sv01	192.152.101.1
group2	monsv02, 192.152.101.3	sv02	192.152.101.2

### 2.3 Enable SNMP monitoring

1. Download the corresponding mib files for your system that you wish to receive SNMP traps from and copy them onto the management node (mn) and the monitoring servers under the following directory:

`/usr/share/snmp/mibs/`

The mib files for IBM blade center management modules (MM) and RSAII are packaged within the firmware updates. They can be found under IBM support page:

<http://www.ibm.com/support/us/en/>

For example,

Download mibs for MM:

- Go to <http://www-304.ibm.com/systems/support/supportsite.wss/docdisplay?lnodocid=MIGR-5070708&brandind=5000020>
- Download file `ibm_fw_amm_bpet26k_anyos_noarch.zip`

- Unzip the file and you will find two mib files `mdblade.mib` and `mmalert.mib`

### Download mibs for RSAII

- Go to <http://www-304.ibm.com/systems/support/supportsite.wss/docdisplay?brandind=5000008&lnidocid=MIGR-64575>
- Download file `ibm_fw_rsa2_ggcp30a_anyos_noarch.zip`
- Unzip it and you will find the mib files `RTRSAAG.MIB` and `RTALSERT.MIB`

### 2. Make sure net-snmp rpm is installed on mn and all the monitoring servers.

```
rpm -qa |grep net-snmp
```

### 3. Add snmpmon to the 'monitoring' table.

```
monadd snmpmon
```

### 4. Configure the Blade Center MM or BMC to set the trap destination to be the management server

```
moncfg snmpmon -r
```

### 5. Start the monitoring

```
monstart snmpmon -r
```

### 6. Set email recipients

When traps are received, they will be logged into the syslog on mn. The warning and critical alerts will be emailed to 'alerts' alias on the mn's mail system. By default, 'alerts' points to the root's mailbox, but you can have the emails sent to other recipients by modifying it. On mn

```
vi /etc/aliases
```

Fine the line beginning with the word `alerts`; it usually is at the bottom of the file.

Change the line so it looks something like this

```
alerts    root, joe@us.ibm.com, jill@yahoo.com
```

Now make the new email aliases in effect

```
newaliases
```

### 7. Set up the filters

xCAT built-in SNMP trap handler can process any SNMP traps. Here is a sample email message sent by the trap handler after a Blade Center MM trap is handled.

```
Subject: Critical: Cluster SNMP Alert!
Message:
Node: rro123b
Machine Type/Model: 0284
Serial Number: 1012ADA
Room:
Rack:
Unit:
Chassis:
Slot:
```

```
SNMP Critical Alert received from bco41(UDP: [11.16.15.41]:161)
App ID: "BladeCenter Advanced Management Module"
App Alert Type: 128
Message: "Processor 2 (CPU 2 Status) internal error"
Blade Name: "rro123b"
Error Source="Blade_11"
```

Trap details:

```
DISMAN-EVENT-MIB::sysUpTimeInstance=17:17:49:12.08
SNMPv2-MIB::snmpTrapOID.0=BLADESPPALT-MIB::mmTrapBladeC
BLADESPPALT-MIB::spTrapDateTime="Date (m/d/y)=05/20/08, Time (h:m:s)=14:30:12"
BLADESPPALT-MIB::spTrapAppId="BladeCenter Advanced Management Module"
BLADESPPALT-MIB::spTrapSpTxtId="bcc41"
BLADESPPALT-MIB::spTrapSysUId="D76ADB0137E2438B9F14DCC6569478BA"
BLADESPPALT-MIB::spTrapSysSern="100058A"
BLADESPPALT-MIB::spTrapAppType=128
BLADESPPALT-MIB::spTrapPriority=0
BLADESPPALT-MIB::spTrapMsgText="Processor 2 (CPU 2 Status) internal error"
BLADESPPALT-MIB::spTrapHostContact="No Contact Configured"
BLADESPPALT-MIB::spTrapHostLocation="No Location Configured"
BLADESPPALT-MIB::spTrapBladeName="rro123b"
BLADESPPALT-MIB::spTrapBladeSern="YL113684L129"
BLADESPPALT-MIB::spTrapBladeUId="3A77351D00001000B6AA001A640F4972"
BLADESPPALT-MIB::spTrapEvtName=2154758151
BLADESPPALT-MIB::spTrapSourceId="Blade_11"
SNMP-COMMUNITY-MIB::snmpTrapAddress.0=11.16.15.41
SNMP-COMMUNITY-MIB::snmpTrapCommunity.0="public"
SNMPv2-MIB::snmpTrapEnterprise.0=BLADESPPALT-MIB::mmRemoteSupTrapMIB
```

But sometimes you want the trap handler filter out certain type of alerts. For example, when blades are rebooting you will get a lot of alerts and you do not want to be notified for these alerts. The filtering can be done by adding a row in the **'monsetting'** table with name equals to `snmpmon` and key equals to `ignore`. The value is a comma separated list that describes the contents in a trap.

For example, to filter out any blade center mm traps from blade `rro123b`.

```
chtab name=snmpmon,key=ignore monsetting.value=BLADESPPALT-
MIB::spTrapBladeName="rro123b"
```

(The `mib` module name `BLADESPPALT-MIB` is optional in the command. `spTrapBladeName` can be found in the `mm` `mib` file or from your email notification.)

The following example will filter out all power on/off/reboot alerts for any blades.

```
chtab name=snmpmon,key=ignore monsetting.value=spTrapMsgText="Blade
powered off",spTrapMsgText="Blade powered on",spTrapMsgText="System
board (Sys Pwr Monitor) power cycle",spTrapMsgText="System board (Sys
Pwr Monitor) power off",spTrapMsgText="System board (Sys Pwr Monitor)
power on",spTrapMsgText="Blade reboot"
```

There are other keys and values for the **'monsetting'** table supported by `snmpmon` monitoring plug-in. For example, you can make user-defined commands to be run for certain traps by adding `'runcmd'` key in the table. Use this command to list all the possible keywords.

```
monls snmpmon -d
```

8. Make sure the blade names on Blade Center MM are identical to the node names defined in the `xCAT` `nodelist` table.

```
rspconfig group1 textid (This command queries the blade name)
n1: textid: SN#YL10338241EA
n2: textid: SN#YL103382513F
n3: textid: SN#YK13A084307Y

rspconfig group1 textid=* (This command sets the blade name)
n1: textid: n1
n2: textid: n2
n3: textid: n3
```

## 9. Verify

Make sure snmpmon is activated.

```
monls snmpmon
      snmpmon    monitored
```

Make sure snmptrapd is up and running on mn and all monitoring servers. And it has -m ALL flag.

```
ps -ef |grep snmptrapd
root 31866 1 0 08:44 ?    00:00:00 /usr/sbin/snmptrapd -m ALL
```

Make sure snmp destination is set to the corresponding monitoring servers.

```
rspconfig mm snmpdest (mm is the group name for all the blade center
management modules)
mm1: SP SNMP Destination 1: 192.152.101.1
mm2: SP SNMP Destination 1: 192.152.101.3
```

Make sure SNMP alert is set to 'enable'

```
rspconfig mm alert
mm1: SP Alerting: enabled
mm2: SP Alerting: enabled
```

(Use `monstop snmpmon -r` to stop the monitoring if desired.)

## 2.4 Enable RMC monitoring

IBM's Resource Monitoring and Control (RMC) subsystem is our recommended software for monitoring xCAT clusters. It's is part of the IBM's Reliable Scalable Cluster Technology (RSCT) that provides a comprehensive clustering environment for AIX and Linux. The RMC subsystem and the core resource managers that ship with RSCT enable you to monitor various resources of your system and create automated responses to changing conditions of those resources. RMC also allows you to create your own conditions (monitors), responses (actions) and sensors (resources).

rmcmon is xCAT's monitoring plug-in module for RMC. It's responsible for automatically setting up RMC monitoring domain for RMC and creates predefined conditions, responses and sensor on the management node, the service node and the nodes. rmcmon also provides node reachability status updates on xCAT **nodelist** table via RMC's node status monitoring.

1. Install RMC *rsct.core*, *rsct.core.utils* and *src* on mn

For Linux, it can be downloaded form here

<http://www14.software.ibm.com/webapp/set2/sas/f/rsct/rmc/download/home.html>

RSCT come swith AIX operating system. However, you need to make sure that the level of software is supported by xCAT. For AIX 5.3, you need at least RSCT 2.4.9.0 which ships with AIX 5.3.0.80 or greater. For AIX 6.1, you need at least RSCT 2.5.1.0 which ships with AIX 6.1.1.0 or greater.

Use this command to check the RSCT level:

```
/usr/sbin/rsct/install/bin/ctversion
```



If you have a lower version of AIX, you can obtain the latest RSCT as part of the AIX Technology Levels, or as separate PTFs.

AIX 6.1

6100-01 TL:

<http://www-933.ibm.com/eserver/support/fixes/fixcentral/pseriesfixpackinformation/6100-01-00-0822>

PTFS:

<http://www-933.ibm.com/eserver/support/fixes/fixcentral/pseriespkgoptions/ptf?fixes=U817016>

AIX 5.3:

5300-08 TL:

<http://www-933.ibm.com/eserver/support/fixes/fixcentral/pseriesfixpackinformation/5300-08-00-0818>

PTFS:

<http://www-933.ibm.com/eserver/support/fixes/fixcentral/pseriespkgoptions/ptf?fixes=U816993>

## 2. Install xCAT-rmc on mn

```
rpm -Uvh xCAT-rmc-2.1.rpm
```

## 3. Setting up xCAT DB

Make sure all the nodes and service nodes that need to have RMC installed have 'osi' in the `nodetype` column of the **nodetype** table.

```
tabdump nodetype
```

Make sure the `mac` column of **mac** table for the nodes and the service nodes are populated because the mac address will be used as a RMC nodeid for the node.

```
tabdump mac
```

## 3. Setting up xCAT hierarchy

Skip this if you have a flat cluster.

`monserver` column of the **noderes** table is used to define a monitoring server for a node. `monserver` is a comma separated pairs of host name or ip addresses. The first one is the monitoring server name or ip known by the mn. The second one is the same host know by the node.

```
chdef -t node -o node5 monserver=9.114.46.47,192.168.52.118
```

If `monserver` is not set, the default is the `servicenode` and `xcatmaster` pair in the **noderes** table.

## 4. Add rmcmon in the 'monitoring' table.

```
monadd rmcmon OR
```

```
monadd rmcmon -n
```

This will also add the `configrmcnode` postscript into **postscripts** table.

The second command allows the RMC monitoring feed the node reachability status monitoring to xCAT. You need to have RSCT 2.4.10.0 or greater on AIX 5.3 system or RSCT 2.5.2.0 or greater on AIX 6.1 for this feature to work.

5. Create resources for IBM.MngNode class to include each node managed by the management node.

```
moncfg rmcmon nodes
```

6. Generate images

Make sure the correct level of *rsct.core*, *rsct.core.utils* and *src* mentioned in step 1 are included in the images for nodes and any monitoring servers. Please refer to step 3 of section 2.1.1.

7. Deploy the nodes and the service nodes as described in the [xCAT 2 cookbook](#). This process will automatically setup the RMC monitoring domain. To verify, list all the nodes managed by mn:

```
CT_MANAGEMENT_SCOPE=4 lsrsrc IBM.Host Name
Resource Persistent Attributes for IBM.Host
resource 1:
    Name = "node1"
resource 2:
    Name = "node2"
```

Use psh command to check the nodes managed by the monitoring servers:

```
psh monserver_name CT_MANAGEMENT_SCOPE=4 lsrsrc IBM.Host Name
```

6. Start RMC monitoring

Now that nodes are installed and configured, you can start the RMC monitoring:

```
monstart rmcmon
```

The `monstart` command actually creates a set of predefined conditions, responses and sensors on the mn and the monitoring servers. To verify:

```
lscondition
lsresponse
lssensor
```

Now you can pick and choose the conditions to monitor using the `startcondresp` command which associates a condition with a response. A condition can be associated with more than one responses.

```
startcondresp AnyNodeVarSpaceUsed EmailRootAnyTime
```

If you have monitoring servers, also turn on the condition with “\_H” in the name.

```
startcondresp AnyNodeVarSpaceUsed_H EmailRootAnyTime
```

Conditions without “\_H” in the name are designed to monitor the nodes which are managed by the mn, whereas conditions with “\_H” in the names are for the nodes managed by the monitoring servers. These nodes are grandchildren of the mn.

With RMC, you can create your own conditions, responses and sensors for monitoring. Please refer to “[RSCT Administration Guide](#)” for details.

## 2.5 Enable node liveness monitoring

xcatmon provides node liveness monitoring using fping. This can be used if no other 3rd party software is used for node status monitoring. The *status* column of the *nodelist* table will be updated periodically with the latest node liveness status by this plug-in.

1. To add the monitoring plug-in in the 'monitoring' table:

```
monadd xcatmon -n -s [ping-interval=5]
```

where 2 means that the nodes are pinged for status every 2 minutes.

2. To activate, use the monstart command:

```
monstart xcatmon
```

3. Verify

Make sure xcatmon is activated.

```
monls snmpmon
xcatmon    monitored node-status-monitored
```

Check the setting

```
tabdump monsetting
#name,key,value,comments,disable
"xcatmon","ping-interval","5",,
```

Make sure cron jobs are activated on mn and all monitoring server

```
crontab -l
*/5 * * * * XCATROOT=/opt/xcat PATH=/bin:/usr/bin:/sbin:/usr/sbin:/opt/xcat/bin:/opt/xcat/sbin /opt/xcat/sbin/xcatnodemon
```

## 2.6 Enable Ganglia monitoring

1. Install Ganglia on the management node

Prerequisites: Apache, PHP and RRD needs to be installed before Ganglia is installed.

RRD installation:

- 1) Download the RRD rpm `rrdtool-1.2.27-3.el5.i386.rpm`
- 2) Install the rpm by using the command

```
rpm -Uvh rrdtool-1.2.27-3.el5.i386.rpm
```

Please note that the versions of the rpms might change and hence download them appropriately.

Ganglia installation:

- 1) Goto "<http://ganglia.sourceforge.net/>" and download the following rpms (under Ganglia monitoring core) :

```
ganglia-gmetad-3.0.7-1.i386.rpm
ganglia-gmond-3.0.7-1.i386.rpm
ganglia-web-3.0.7-1.noarch.rpm
```

Please note that the versions of the rpms might change and hence download them appropriately.

- 2) Install the above rpms by using the rpm commands:

```
rpm -Uvh ganglia-gmetad-3.0.7-1.i386.rpm ganglia-gmond-3.0.7-1.i386.rpm ganglia-web-3.0.7-1.noarch.rpm
```

## 2. Setting up xCAT DB

Make sure all the nodes and service nodes that need to Ganglia installed have 'osi' in the `nodetype` column of the `nodetype` table.

```
tabdump nodetype
```

3. Make sure that “gangliamon” is added to the “monitoring” table by using the command

```
monadd gangliamon
```

This command will also add the 'confGang' configuration scripts on the 'postscripts' table.

4. Install Ganglia on the service node and the compute nodes.

1) Copy `ganglia-gmetad-3.0.7-1.i386.rpm` and `ganglia-gmond-3.0.7-1.i386.rpm` to `/install/post/otherpkgs/<osver>/<arch>` directory

2) Add `ganglia-gmetad` and `ganglia-gmond` to the service node's 'other packages' profile (`service.otherpkgs.pkglist`) and save it to `/install/custom/<install|netboot>/os` directory.

3) Add `ganglia-gmond` to the compute node's 'other packages' profile (`compute.otherpkgs.pkglist`) and save it to `/install/custom/<install|netboot>/os` directory. Please refer to [xCAT 2 How to Install Additional Software](#) for details.

4) install the service node and then compute nodes. Please refer to the [xCAT 2 cookbook](#) for details. This step will run the 'confGang' postscript on all the nodes which configures the Ganglia to use unicast modd.

5. Configure management node and the service nodes

```
moncfg gangliamon
```

No need to specify `-r` option because the nodes are configured during the deployment phase.

6. Starting gangliamon:

```
monstart gangliamon -r
```

The `-r` flag will ensure that the Ganglia daemon (`gmond`) on the node is started.

Note: Use this command to stop gangliamon:

```
monstop gangliamon -r
```

## 2.7 Enable PCP (Performance Co-Pilot) monitoring

1. Install PCP on the management node.

PCP installation:

1) Goto “[ftp://oss.sgi.com/projects/pcp/download/](http://oss.sgi.com/projects/pcp/download/)” and download the rpms for PCP `pcp-2.7.7-20080924.i386.rpm`

Please note that the versions of the rpm might change and hence download them appropriately.

2) Install the above rpm by using the rpm commands:

```
rpm -Uvh pcp-2.7.7-20080924.i386.rpm
```

## 2. Setting up xCAT DB

Make sure all the nodes and service nodes that need to have PCP installed have 'osi' in the `nodetype` column of the `nodetype` table.

```
tabdump nodetype
```

3. Make sure that “pcpmon” is added to the “monitoring” table by using the command

```
monadd pcpmon or use
```

```
monadd pcpmon -n to use PCP to monitor node status.
```

4. Install PCP on the service node and the compute nodes.

1) Copy `pcp-2.7.7-20080924.i386.rpm` to `/install/post/otherpkgs/<osver>/<arch>` directory

2) Add `pcp` to the service node's 'other packages' profile

(`service.otherpkgs.pkglist`) and save it to `/install/custom/<install|netboot>/os` directory.

3) Add `pcp` to the compute node's 'other packages' profile

(`compute.otherpkgs.pkglist`) and save it to `/install/custom/<install|netboot>/os` directory. Please refer to [xCAT 2 How to Install Additional Software](#) for details.

4) install the service node and then compute nodes. Please refer to the [xCAT 2 cookbook](#) for details.

5. “pcpmon” allows the users to collect the performance monitoring metrics which they desire. The metrics are inputted through a configuration file called “pcpmon.config” located under “`$.:XCATROOT/lib/perl/xCAT_monitoring/pcp/`”. There is no limit on the number of metrics that can be collected as long as all the metrics are legal in the PCP context and the user can update the configuration file periodically to add/remove metrics. To know the valid metrics in PCP use the “`pminfo`” command. A typical “pcpmon.config” file could look like this:

```
mem.physmem
mem.util.free
mem.util.swapFree
fileys.used
proc.memory.size
disk.dev.total
```

6. The metrics are updated in the xCAT database table called “performance”. A typical entry in the “performance” table could look like this:

```
#timestamp,node,attrname,attrvalue
"10/08/08:16:21:18", "cu03sv", "mem.physmem", "1925460.000"
```

```
"10/08/08:16:21:18", "cu03sv", "mem.util.free", "179448.000"  
"10/08/08:16:21:18", "cu03sv", "mem.util.swapFree", "1052216.000"  
"10/08/08:16:21:18", "cu03sv", "filesystems.used", "10224392.000"  
"10/08/08:16:21:18", "cu03sv", "proc.memory.size", "92.000"  
"10/08/08:16:21:18", "cu03sv", "disk.dev.total", "10316.000"
```

### 7. Starting pcpmon:

```
monstart pcpmon -r
```

The -r flag will ensure that the PCP daemon on the node is started.

Note: Use this command to stop pcpmon:

```
monstop pcpmon -r
```

## 2.8 Enable node liveness monitoring with PCP

“pcpmon” provides node liveness monitoring. This can be used if no other 3rd party software is used for node status monitoring. The *status* column of the *nodelist* table will be updated periodically with the latest node liveness status by this plug-in.

1. To add the monitoring plug-in in the 'monitoring' table:

```
monadd pcpmon -n -s [ping-interval=15]
```

Please note that the above command will set the interval to 15 minutes and the default (if “ping-interval” is not used) is 5 minutes.

2. To activate, use the monstart command:

```
monstart pcpmon
```

3. Verify

Make sure pcpmon is activated.

```
monls pcpmon  
pcpmon          monitored          node-status-monitored
```

Check the setting

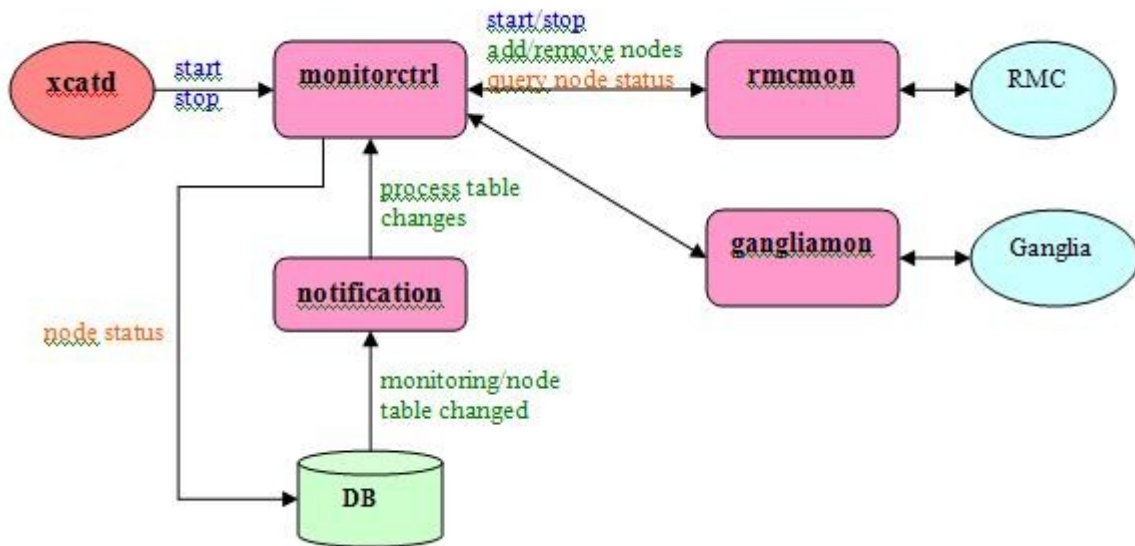
```
tabdump monsetting  
#name, key, value, comments, disable  
"xcatmon", "ping-interval", "15", ,
```

Make sure cron jobs are activated on MN and all monitoring server

```
crontab -l  
*/15 * * * * XCATROOT=/opt/xcat  
PATH=/sbin:/usr/sbin:/bin:/usr/bin:/opt/xcat/bin:/opt/xcat/sbin  
/opt/xcat/sbin/pcp_collect
```

## 2.9 Create your own monitoring plug-in module

As mentioned before, a monitoring plug-in module acts as a bridge to connect xCAT and the 3rd party software. The functions of a monitoring plug-in module include initializing the 3rd party software, informing it with the changes of the xCAT node list, setting it up to feed node status back to xCAT etc. The following figure depicts the data flow and the relationship among xcatd, monitoring plug-ins and the third party software.



**Figure 2. Data flow among xcatd, plug-in modules and 3rd party monitoring software**

To use this infrastructure to create your own plug-in module, create a Perl module and put it under `/opt/xcat/lib/perl/xCAT_monitoring/` directory. If the file name is `xxx.pm` then the package name will be `xCAT_monitoring::xxx`. The following is a list of subroutines that a plug-in module must implement:

```

start
stop
config
deconfig
supportNodeStatusMon
startNodeStatusMon
stopNodeStatusMon
processSettingChanges (optional)
getDiscription
getPostscripts (optional)
getNodeConfData (optional)

```

Please refer to `/opt/xcat/lib/perl/xCAT_monitoring/samples/tmplatemon.pm` for the detailed description of the functions. You can find `tmplatemon.pm` from the xCAT source code on the web: <http://xcat.svn.sourceforge.net/viewvc/xcat/xcat-core/trunk/xCAT-server-2.0/lib/xcat/monitoring/samples/>

### 3.0 Using xCAT Notification Infrastructure

With xCAT 2.0, you can monitor xCAT database for changes such as nodes entering/leaving the cluster, hardware updates, node liveness etc. In fact anything stored in the xCAT database tables can be monitored through the xCAT notification infrastructure. To start getting notified for changes, simply register your Perl module or command as the following:

```
regnotif filename tablename -o actions
```

where

*filename* is the full path name of your Perl module or command.

*tablename*s is a comma separated list of table names that you are interested in.

*actions* is a comma separated list of data table actions. 'a' for row addition, 'd' for row deletion and 'u' for row update.

Example:

```
regnotif /opt/xcat/lib/perl/xCAT_monitoring/mycode.pm nodelist,nodhm  
-o a,d
```

```
regnotif /usr/bin/mycmd switch,noderes -o u
```

Use the following command to view all the modules and commands registered.

```
tabdump notification
```

To unregister, just do the following:

```
unregnotif filename
```

Example:

```
unregnotif /opt/xcat/lib/perl/xCAT_monitoring/mycode.pm
```

```
unregnotif /usr/bin/mycmd
```

If the *filename* specifies a Perl module, the package name must be **xCAT\_monitoring::xxx**. It must implement the following subroutine which will get called when database table change occurs:

```
processtbChanges(tableop, table_name, old_data, new_data)
```

where:

*tableop* Table operation. It can be 'a' for row addition, 'd' for row deletion and 'u' for row update.

*tablename* The name of the database table whose data has been changed.

*old\_data* An array reference of the old row data that has been changed. The first element is an array reference that contains the column names. The rest of the elements are array references each contains attribute values of a row. It is set when the action is u or d.

*new\_data* A hash reference of the new row data; only changed values are in the hash. It is keyed by column names. It is set when the action is u or a.



If the file name specifies a command (written by any programming languages or scripts), when the interested database table changes, the info will be fed to the command through the standard input. The format of the data in the STDIN is as following:

```
action(a, u or d)
tablename
[old value]
col1_name,col2_name...
col1_val,col2_val,...
col1_val,col2_val,....
...
[new value]
col1_name,col2_name,...
col1_value,col2_value,...
...
```

The sample code can be found under

/opt/xcat/lib/perl/xCAT\_monitoring/samples/mycode.pm on a installed system or on the web <http://xcat.svn.sourceforge.net/viewvc/xcat/xcat-core/trunk/xCAT-server-2.0/lib/xcat/monitoring/samples/>