

# XCAT 2 High Availability Management Node Setup

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Note: If DB2 is used in your cluster, this documentation only works for xCAT 2.5 or beyond.

## 1.0 Overview

This documentation illustrates how to setup the second management node, or standby management node, in your cluster to provide high availability management capability.

With the primary management node fails, the administrator can easily have the standby management node take over the management node role, thus avoid long duration of a bad state that the cluster does not have management node available.

The xCAT high availability management node(HAMN) feature is not designed for automatic setup or automatic failover in this version, this documentation will describe how to synchronize various data between the primary management node

and standby management node automatically, and describe how to perform some manual steps to have the standby management node takeover the management node role when fail occurs on the primary management node.

## 2.0 Configuration Requirements

xCAT HAMN requires the operating system version, xCAT version and database version are identical on the two management nodes.

The hardware type/model are not required to be the same on the two management nodes, but it is recommended to have similar hardware capability on the two management nodes to support the same operating system and have similar management capability.

Since the management node needs to provide IP services through broadcast such as DHCP to the compute nodes, the primary management node and standby management node should be in the same subnet to make the network services could work after failover.

The HAMN setup can be performed at any time during the life of the cluster. This documentation assumes the HAMN setup is performed from the very beginning of the cluster setup. You can skip the corresponding steps in case part of the setup has already been done in your cluster.

The twin-tailed disks are not required, different methods are used to ensure the data synchronization between the primary management node and standby management node, however, if you have the twin-tailed disks in cluster, then the data synchronization will be easier, you can put the related directories and files mentioned in section **Setup Database Replication** and section **Files Synchronization** onto the twin-tailed disks, re-mount the twin-tailed disks to the standby management node during the failover, the corresponding steps to keep the data synchronized can be skipped.

The steps in this documentation are based on a real cluster environment:

*Primary Management Node: aixmn1(9.114.47.103) running AIX 6.1L and DB2 9.7*

*Standby Management Node: aixmn2(9.114.47.104) running AIX 6.1L and DB2 9.7*

You need to substitute the hostnames and ip address with yours when setting up your own HAMN environment.

## 3.0 Setup Primary Management Node

The procedure described in [xCAT2 Top Doc](#) can be used for the primary management node setup. If DB2 will be used as the xCAT database system, please refer to the doc [Setup DB2 as the xCAT Database](#).

## 4.0 Setup Standby Management Node

The procedure described in [xCAT2 Top Doc](#) can also be used for the standby management node setup. The database system on the standby management node should be the same as the one running on the primary management node.

After the standby management node setup is done, perform the following additional configuration steps:

1. Make sure the primary management node can resolve the hostname of the standby management node, and vice versa.
2. Setup ssh authentication between the primary management node and standby management node.
3. Make sure the time on the primary management node and standby management node is synchronized.
4. Stop the xcatd daemon and DHCP service.

## 5.0 Setup Database Replication

The most important data that needs to be kept synchronized on the primary management node and standby management node is the xCAT database. Most of the commercial database systems and some free database systems such as Postgresql and MySQL provide database replication feature, the database replication feature can be used for high availability capability. The configuration for database replication is quite different with various database systems, so this documentation can not cover all of the configuration scenarios. This documentation will focus on database replication configuration for DB2, and will also provide some documentation link for the replication setup for some other database systems.

### 5.1 DB2 High Availability Disaster Recovery (HADR) Setup

DB2 High Availability Disaster Recovery (HADR) is a database replication feature that provides a high availability solution. HADR transmits the log records from the primary database server to the standby server. The HADR standby replays all the log records to its copy of the database, keeping it synchronized with the primary database server. Applications can only access the primary database and have no access to the standby database.

HADR communication between the primary and the standby is through TCP/IP, so the primary database server and standby database server do not need to be in the same subnet.

This documentation will only describe some basic configuration steps for HADR setup, there might be some configuration deviations in different cluster environment, please refer to the following links for more details:

1. Redbook “High Availability and Disaster Recovery Options for DB2 on

Linux UNIX and Windows”

<http://www.redbooks.ibm.com/abstracts/sg247363.html>

2. DB2 Information Center

<http://publib.boulder.ibm.com/infocenter/db2luw/v9r5/index.jsp?topic=/com.ibm.db2.luw.admin.ha.doc/doc/c0011748.html>

Please be aware that all the DB2 commands in this section should be run as xcatdb unless otherwise noted.

### 5.1.1 Disconnect all the DB2 Clients

Before proceeding with the DB2 HADR setup, all the DB2 clients should be disconnected from the DB2 database sever. For xCAT environment, the only DB2 clients should be xcatd, so the xcatd on both management node and service nodes need to be stopped.

### 5.1.2 Setup configuration parameters for xcatdb

Several configuration parameters need to be updated for HADR

```
db2 UPDATE DB CFG FOR XCATDB USING LOGRETAIN ON
db2 UPDATE DB CFG FOR XCATDB USING TRACKMOD ON
db2 UPDATE DB CFG FOR XCATDB USING LOGINDEXBUILD ON
db2 UPDATE DB CFG FOR XCATDB USING INDEXREC RESTART
```

### 5.1.3 Backup xcatdb on Primary Management Node

The xcatdb on the primary management node and standby management node should be synchronized before setting up the HADR, otherwise, we will run into errors when trying to start HADR.

```
db2 BACKUP DB XCATDB TO /var/lib/db2/backup/
```

The command output will be something like:

```
Backup successful. The timestamp for this backup image
is : 20100805161232
```

*Note: if you get an error, like “SQL1035N The database is currently in use. SQLSTATE=57019”, make sure your xcatd daemons on management node and service nodes are not running, deactivating the xcatdb using command “db2 DEACTIVATE DB XCATDB” may also be helpful.*

### 5.1.4 Restore xcatdb on Standby Management Node

Copy the xcatdb backup from the primary management node to standby management node:

```
scp -r backup xcatdb@aixmn2:/var/lib/db2/
```

Restore the xcatdb database:

```
db2 RESTORE DATABASE XCATDB FROM "/var/lib/db2/backup"  
TAKEN AT 20100805161232 REPLACE HISTORY FILE
```

You will be prompted with the following question:

```
SQL2539W Warning! Restoring to an existing database  
that is the same as the  
backup image database. The database files will be  
deleted.  
Do you want to continue ? (y/n)
```

Answer: y

### 5.1.5 Configure HADR services ports

Add the following lines into /etc/services on both the primary management node and standby management node, you need to run as root to edit /etc/services.

```
DB2_HADR_1      55001/tcp  
DB2_HADR_2      55002/tcp
```

### 5.1.6 Configure the HADR Parameters

Use the following commands to configure the HADR parameters:

On primary management node:

```
db2 UPDATE ALTERNATE SERVER FOR DATABASE XCATDB USING  
HOSTNAME 9.114.47.104 PORT 60000  
db2 UPDATE DB CFG FOR XCATDB USING HADR_LOCAL_HOST  
9.114.47.103  
db2 UPDATE DB CFG FOR XCATDB USING HADR_LOCAL_SVC  
DB2_HADR_1  
db2 UPDATE DB CFG FOR XCATDB USING HADR_REMOTE_HOST  
9.114.47.104  
db2 UPDATE DB CFG FOR XCATDB USING HADR_REMOTE_SVC  
DB2_HADR_2  
db2 UPDATE DB CFG FOR XCATDB USING HADR_REMOTE_INST  
xcatdb  
db2 UPDATE DB CFG FOR XCATDB USING HADR_SYNCMODE  
NEARSYNC  
db2 UPDATE DB CFG FOR XCATDB USING HADR_TIMEOUT 3  
db2 UPDATE DB CFG FOR XCATDB USING HADR_PEER_WINDOW 120
```

```
db2 UPDATE DB CFG FOR XCATDB USING
db2 CONNECT TO XCATDB
db2 QUIESCE DATABASE IMMEDIATE FORCE CONNECTIONS
db2 UNQUIESCE DATABASE
db2 CONNECT RESET
```

On Standby management node:

```
db2 UPDATE ALTERNATE SERVER FOR DATABASE XCATDB USING
HOSTNAME 9.114.47.103 PORT 60000
db2 UPDATE DB CFG FOR XCATDB USING HADR_LOCAL_HOST
9.114.47.104
db2 UPDATE DB CFG FOR XCATDB USING HADR_LOCAL_SVC
DB2_HADR_2
db2 UPDATE DB CFG FOR XCATDB USING HADR_REMOTE_HOST
9.114.47.103
db2 UPDATE DB CFG FOR XCATDB USING HADR_REMOTE_SVC
DB2_HADR_1
db2 UPDATE DB CFG FOR XCATDB USING HADR_REMOTE_INST
xcatdb
db2 UPDATE DB CFG FOR XCATDB USING HADR_SYNCMODE
NEARSYNC
db2 UPDATE DB CFG FOR XCATDB USING HADR_TIMEOUT 3
db2 UPDATE DB CFG FOR XCATDB USING HADR_PEER_WINDOW 120
```

Substitute the IP addresses in the example with yours.

### 5.1.7 Start HADR

On standby management node, start HADR as the standby database:

```
db2 DEACTIVATE DATABASE XCATDB
db2 START HADR ON DATABASE XCATDB AS STANDBY
```

On primary management node, start HADR as the primary database:

```
db2 DEACTIVATE DATABASE XCATDB
db2 START HADR ON DATABASE XCATDB AS PRIMARY
```

If you get any message other than “*DB20000I The START HADR ON DATABASE command completed successfully*”, make sure all the steps described above have been done correctly, or refer to the DB2 information center for troubleshooting.

### 5.1.8 Verify HADR Status

HADR can be in wrong state even if the “START HADR” command returns successfully, command “db2 GET SNAPSHOT FOR DB ON XCATDB” or “db2pd -d xcatdb -hadr” can be used to verify HADR status, the HADR status output is quite similar between these two commands, here is an example:

**db2 GET SNAPSHOT FOR DB ON XCATDB**

HADR Status  
Role = Primary  
State = Peer  
Synchronization mode = Nearsync  
Connection status = Connected, 08/05/2010  
20:33:00.412948  
Peer window end = 08/05/2010 21:03:07.000000  
(1281013387)  
Peer window (seconds) = 120  
Heartbeats missed = 0  
Local host = 9.114.47.103  
Local service = DB2\_HADR\_1  
Remote host = 9.114.47.104  
Remote service = DB2\_HADR\_2  
Remote instance = xcatdb  
timeout(seconds) = 3  
Primary log position(file, page, LSN) = S0000002.LOG,  
18, 000000000FA18D7C  
Standby log position(file, page, LSN) = S0000002.LOG,  
18, 000000000FA18D7C  
Log gap running average(bytes) = 0

**db2pd -d xcatdb -hadr**

Database Partition 0 -- Database XCATDB -- Active -- Up  
0 days 01:17:11

HADR Information:  
Role State SyncMode HeartBeatsMissed  
LogGapRunAvg (bytes)  
Primary Peer Nearsync 0  
0

ConnectStatus ConnectTime  
Timeout  
Connected Thu Aug 5 20:33:00 2010 (1281011580) 3

PeerWindowEnd PeerWindow  
Thu Aug 5 21:52:07 2010 (1281016327) 120

LocalHost LocalService  
9.114.47.103 DB2\_HADR\_1

RemoteHost RemoteService  
RemoteInstance  
9.114.47.104 DB2\_HADR\_2  
xcatdb

PrimaryFile PrimaryPg PrimaryLSN  
S0000002.LOG 66 0x000000000FA4869D

```
StandByFile StandByPg StandByLSN
S0000002.LOG 66 0x000000000FA4869D
```

The attributes “Role”, “State” and “ConnectStatus” need to be checked, for an operating HADR environment, the “Role” should be “Primary” or “Standby”; the “State” should be “Peer” and the “ConnectStatus” should be “Connected”. If any of the attribute is not correct, you need to go back to check the HADR settings and try to restart the HADR, if the problem persists, refer to DB2 documentation or contact DB2 service team.

### 5.1.9 Test Database Synchronization

After the HADR setup is done, we should verify the database synchronization between the primary management node and standby management node. Here are the recommended steps:

On primary management node:

- 1) start xcatd
- 2) Add a new testnode
- 3) stop xcatd

On standby management node:

- 1) Takeover as the HADR primary using command “db2 TAKEOVER HADR ON DATABASE XCATDB USER xcatdb USING cluster”
- 2) start xcatd
- 3) Verify the testnode is in database and the node attributes are correct
- 4) Delete the testnode from database
- 5) stop xcatd

On primary management node:

- 1) Takeover as the HADR primary using command “db2 TAKEOVER HADR ON DATABASE XCATDB USER xcatdb USING cluster”
- 2) start xcatd
- 3) Verify the testnode is not in the database

### 5.1.10 Some useful HADR commands

Besides the HADR related commands described above, there are still some other HADR commands that are useful for administration and debugging:



## 1. Stop HADR

```
db2 STOP HADR ON DATABASE XCATDB
```

Note: On the HADR standby database server, after the HADR is stopped, the database is in “ROLL-FORWARD PENDING” state and the xcatdb can not be activated with error “SQL1117N A connection to or activation of database "XCATDB" cannot be made because of ROLL-FORWARD PENDING. SQLSTATE=57019”, the command “db2 ROLLFORWARD DATABASE XCATDB TO END OF LOGS AND COMPLETE” can be used to fix this problem.

## 2. Check xcatdb configuration

```
db2 CONNECT TO XCATDB
db2 GET DB CFG
```

## 3. Takeover HADR role

```
db2 TAKEOVER HADR ON DATABASE XCATDB USER xcatdb USING
cluster
OR
db2 TAKEOVER HADR ON DATABASE XCATDB USER xcatdb USING
cluster BY FORCE
```

The “BY FORCE” option should be used only if the primary database server is not functional.

## **5.2 Database Replication for Postgresql**

Postgresql does provide feature “Continuous Archiving and Point-In-Time Recovery (PITR)” that can be used to provide high availability cluster configuration, see <http://www.postgresql.org/docs/8.4/interactive/warm-standby.html> and <http://www.postgresql.org/docs/8.4/interactive/continuous-archiving.html> for more details.

But this feature actually uses the “backup on the primary database server” and “restore on the standby database server”, PITR is not real-time replication, the backup interval is configured manually in the postgresql.conf file, the recovery interval is configured in recovery.conf, it will save a lot of database logging files and the logging files take big amount of disk space. Based on the considerations above, using the database backup command `pg_dump` and restore command `pg_restore` is seems to be a better solution for the xCAT database replication.

### **On the primary management node**

add crontab entries to:

1. dump the xcatdb into a file
2. scp the xcatdb backup file to the standby management node

Here is an example of the crontab entries for user postgres:

```
0 3 * * * /var/lib/pgsql/bin/pg_dump -f /tmp/xcatdb -F t
xcatdb
```

Here is an example of the crontab entries for user root:

```
0 4 * * * scp /tmp/xcatdb aixmn2:/tmp/
```

### **On the standby management node:**

stop the xcatd and Postgresql.

AIX:

```
Stopsrc -s xcatd
su - postgres
/var/lib/pgsql/bin/pg_ctl -D /var/lib/pgsql/data stop
```

Linux:

```
service xcatd stop
su - postgres
service postgresql stop
```

Add crontab entry to restore the database, here is an example of the crontab entries for user postgres:

```
0 5 * * * /var/lib/pgsql/bin/pg_restore -d xcatdb -c
/tmp/xcatdb
```

## **5.3 Database Replication for Other Database Systems**

This documentation will not cover the details for setting up replication for the database systems other than DB2, here are some useful links for setting up database replication for various database systems supported by xCAT.

MySQL: <http://dev.mysql.com/doc/refman/5.5/en/replication.html>

sqlite: sqlite does not provide replication feature, but since the sqlite is file-based database, so you can use file copy or synchronization mechanism on Unix/Linux to achieve the database synchronization.

## **6.0 Files Synchronization**

To make the standby management node be ready for an easy take over, there are a lot files should be kept synchronized between the primary management node and standby management node.

A straightforward way to keep files synchronized is to use rsync, and the crontab can make the synchronization be automatic. This documentation will use the rsync and crontab as the files synchronization solution, you can use your own files synchronization solution as long as it could keep the corresponding files be synchronized between the primary management node and standby management node.

## 6.1 SSL Credentials and SSH Keys

The SSL credentials need to be identical on the primary management node and standby management node, the xcatd request submit from service nodes and compute nodes depend on the SSL credentials.

To setup the ssh authentication between the primary management node, standby management node, service nodes and compute nodes, the ssh keys should be kept synchronized between the primary management node and standby management node.

The SSL credentials reside in directory /etc/xcat/ca, /etc/xcat/cert and \$HOME/.xcat/, the ssh keys are in directory /etc/xcat/hostkeys.

Here is an example of the crontab entries for synchronizing the SSL credentials and SSH keys:

```
0 1 * * * /usr/bin/rsync -az /etc/xcat/ca /etc/xcat/cert
/etc/xcat/hostkeys aixmn2:/etc/xcat
0 1 * * * rsync -az $HOME/.xcat aixmn2:$HOME/
```

## 6.2 Node Deployment Packages

The node deployment packages are under the directory specified by the “installdir” in site table, the default location is /install directory. The node deployment packages need to be synchronized to the standby management node.

For Linux, it will be easy to achieve this by copying the whole /install directory from the primary management node to the standby management node; however, copying the whole /install directory is not enough for AIX, we will have to create the NIM resources on the standby management node. Some manual steps are required to create the NIM resources on the backup management node.

Here is an example of the crontab entries for synchronizing the node deployment packages:

```
0 2 * * * /usr/bin/rsync -az /install aixmn2:/
```

If you do not want to do the manual steps on the standby management node to re-create the NIM resources, the AIX feature High Availability Network Installation Manager(HANIM) can be used for keeping the NIM resources synchronized between the primary management node and standby management node. Please refer to AIX redbook “NIM from A to Z in AIX 5L” at <http://www.redbooks.ibm.com/redbooks/pdfs/sg247296.pdf> for more details about HANIM.

## 6.3 Network Services Configuration Files

A lot of network services are configured on management node, such as DNS, DHCP and HTTP, the network services are mainly controlled by the configuration files,

however, some of the network services configuration files contain the local hostname/ipaddresses related information, so simply copying these network services configuration files to the standby management node may not work, considering that generating these network services configuration files are very easy and quick by running xCAT commands such as `makedhcp`, `makedns` or `nimnodeset`, as long as the xCAT database contains correct information. It will be easier to configure the network services on the standby management node by running xCAT commands when failing over to the standby management node. An exception is the `/etc/hosts` and `/etc/resolve` files, the `/etc/hosts` and `/etc/resolv.conf` may be modified as cluster maintenance activities, the `/etc/hosts` and `/etc/resolv.conf` are very important for xCAT commands, so the `/etc/hosts` and `/etc/resolv.conf` will be synchronized between the primary management node and standby management node. Here is an example the crontab entries for synchronizing the `/etc/hosts` and `/etc/resolv.conf`:

```
0 2 * * * /usr/bin/rsync -az /etc/hosts /etc/resolv.conf
aixmn2:/etc/
```

## 7.0 Cluster Maintenance Considerations

The standby management node should be taken into account when doing any maintenance work in the xCAT cluster with HAMN setup.

1. Software Maintenance

Any software update on the primary management node should also be done on the standby management node.

2. Files Synchronization

Although we have setup crontab to synchronize the related files between the primary management node and standby management node, but the crontab entries are only run in some specific time slots, the synchronization delay brings in potential problems with HAMN, so it is recommended to manually synchronize the files mentioned in the section above whenever the files are modified.

## 8.0 Failover

When the primary management node fails for whatever reason, the administrator should start the failover process, some manual steps are involved in the failover process.

1. Failover the database replication, use the description in the section “setup database replication” to failover the database replication to the standby management node.

2. Shutdown the primary management node

If the primary management node is not totally dead, shutdown the primary management node. The standby management node could not take over the management role if the primary management node is still up, because the

standby management node will be configured with the hostname and ip address that the primary management was configured.

3. Stop the database system on the standby management node. Take DB2 as an example, the following commands can be used to stop the DB2:

```
db2 STOP HADR ON DATABASE XCATDB
db2 connect reset
db2 force applications all
db2 terminate
db2stop
```

4. On the standby management node, change the ip address and hostname configured on cluster-facing adapter on the standby management node to the ones were configured on the primary management node. Here is an example:

```
/usr/sbin/mktcpip -h'aixmn1' -a'9.114.47.103'
-m'255.255.255.192' -i'en1' -g'9.114.47.126' -A'no'
-t'N/A' -s''
```

5. Update database configuration to use the new ip address and new hostname. For DB2, use the following command:

```
db2gcf -u -p 0 -i xcatdb
```

This command will update the DB2 database configuration file “*/var/lib/db2/sqllib/db2nodes.cfg*” and start DB2.

For Postgres, update the line “host all all x.x.x.x/32 md5” in file */var/lib/pgsql/postgresql.conf* and update the line “listen\_addresses = 'x.x.x.x'” in file */var/lib/pgsql/pg\_hba.conf*.

6. Start xcatd on the standby management node.
7. Setup the network services and:
  1. DNS: run `makedns`
  2. DHCP(Linux only): run `makedhcp`
  3. conserved: `makeconserved`
8. Setup os deployment environment
  1. Create operating system images:
    1. For Linux: the operating system images definitions are ready in xCAT database, and the operating system images files are already in */install* directory.
    2. For AIX: If the HANIM is being used for keeping the NIM resources synchronized, then no manual steps are needed to create the NIM resources on the standby management node; otherwise, the operating systems images files are in */install* directory, but have to create the NIM resources manually. Refer to the xCAT AIX documents listed at <http://xcat.svn.sourceforge.net/viewvc/xcat/xcat-core/trunk/xCAT-client/share/doc/index.html> for more details on how to create the NIM resources. Here are some manual steps that can be referred for re-creating the NIM resources:
      1. If the nim master is not initialized, run command “`nim_master_setup -a mk_resource=no -a device=<source directory>`” to initialize the NIM master, where the *<source directory>*

- directory*> is the directory that contains the AIX installation image files.
2. Run “lsdef -t osimage -l” to list all the AIX operating system images.
  3. For each osimage:
    1. Create the lpp\_source resource: /usr/sbin/nim -Fo define -t lpp\_source -a server=master -a location=/install/nim/lpp\_source/<osimagenam>\_lpp\_source <osimagenam>\_lpp\_source
    2. Create the spot resource: /usr/lpp/bos.sysmgt/nim/methods/m\_mkspot -o -a server=master -a location=/install/nim/spot/ -a source=no <osimage>
    3. Check if the osimage has any kind of the following resources: "installp\_bundle", "script", "root", "shared\_root", "tmp", "home", "shared\_home", "dump" and "paging". If yes, use commands “/usr/sbin/nim -Fo define -t <type> -a server=master -a location=<location> <osimagenam>\_<type>” to create all the necessary nim resources, where the <location> is the resource location returned by “lsdef -t osimage -l” command.
2. Run nodeset, nimnodeset or mkdsklsnode

## 9.0 Failback

When the previous primary management node is back up and running, you may want to failback to the primary management node, since the xCAT database and related files are not up to date on the previous primary management node when it is down. So failing back to the the previous primary management node is not an easy action, you can go through all the steps described in this documentation to setup the previous standby management node as the new primary management node and setup the previous primary management node as the new standby management node, and then do a failover from the new primary management node to the new standby management node.

## 10.0 References

- Redbook “High Availability and Disaster Recovery Options for DB2 on Linux UNIX and Windows”  
<http://www.redbooks.ibm.com/abstracts/sg247363.html>
- DB2 Information Center  
<http://publib.boulder.ibm.com/infocenter/db2luw/v9r5/index.jsp?topic=/com.ibm.db2.luw.admin.ha.doc/doc/c0011748.html>
- [Setup DB2 as the xCAT Database](#)

- <http://www.postgresql.org/docs/8.4/interactive/warm-standby.html>
- [http://wiki.postgresql.org/wiki/Replication,\\_Clustering,\\_and\\_Connection\\_Pooling](http://wiki.postgresql.org/wiki/Replication,_Clustering,_and_Connection_Pooling)